

Nonhomogeneous Linear Equations

THEOREM 7 The general solution $y = y(x)$ to the nonhomogeneous differential equation (1) has the form

$$y = y_c + y_p,$$

where the **complementary solution** y_c is the general solution to the associated homogeneous equation (2) and y_p is any **particular solution** to the nonhomogeneous equation (1).

■ The Method of Undetermined Coefficients

We first illustrate the method of undetermined coefficients for the equation

$$ay'' + by' + cy = G(x)$$

where $G(x)$ is a polynomial. It is reasonable to guess that there is a particular solution y_p that is a polynomial of the same degree as G because if y is a polynomial, then $ay'' + by' + cy$ is also a polynomial. We therefore substitute $y_p(x) =$ a polynomial (of the same degree as G) into the differential equation and determine the coefficients.

EXAMPLE 1 Solve the equation $y'' + y' - 2y = x^2$.

SOLUTION The auxiliary equation of $y'' + y' - 2y = 0$ is

$$r^2 + r - 2 = (r - 1)(r + 2) = 0$$

with roots $r = 1, -2$. So the solution of the complementary equation is

$$y_c = c_1 e^x + c_2 e^{-2x}$$

Since $G(x) = x^2$ is a polynomial of degree 2, we seek a particular solution of the form

$$y_p(x) = Ax^2 + Bx + C$$

Then $y_p' = 2Ax + B$ and $y_p'' = 2A$ so, substituting into the given differential equation, we have

$$(2A) + (2Ax + B) - 2(Ax^2 + Bx + C) = x^2$$

or

$$-2Ax^2 + (2A - 2B)x + (2A + B - 2C) = x^2$$

Polynomials are equal when their coefficients are equal. Thus

$$-2A = 1 \quad 2A - 2B = 0 \quad 2A + B - 2C = 0$$

The solution of this system of equations is

$$A = -\frac{1}{2} \quad B = -\frac{1}{2} \quad C = -\frac{3}{4}$$

A particular solution is therefore

$$y_p(x) = -\frac{1}{2}x^2 - \frac{1}{2}x - \frac{3}{4}$$

and, by Theorem 3, the general solution is

$$y = y_c + y_p = c_1e^x + c_2e^{-2x} - \frac{1}{2}x^2 - \frac{1}{2}x - \frac{3}{4} \quad \blacksquare \blacksquare$$

If $G(x)$ (the right side of Equation 1) is of the form Ce^{kx} , where C and k are constants, then we take as a trial solution a function of the same form, $y_p(x) = Ae^{kx}$, because the derivatives of e^{kx} are constant multiples of e^{kx} .

EXAMPLE 2 Solve $y'' + 4y = e^{3x}$.

SOLUTION The auxiliary equation is $r^2 + 4 = 0$ with roots $\pm 2i$, so the solution of the complementary equation is

$$y_c(x) = c_1 \cos 2x + c_2 \sin 2x$$

For a particular solution we try $y_p(x) = Ae^{3x}$. Then $y'_p = 3Ae^{3x}$ and $y''_p = 9Ae^{3x}$. Substituting into the differential equation, we have

$$9Ae^{3x} + 4(Ae^{3x}) = e^{3x}$$

so $13Ae^{3x} = e^{3x}$ and $A = \frac{1}{13}$. Thus, a particular solution is

$$y_p(x) = \frac{1}{13}e^{3x}$$

and the general solution is

$$y(x) = c_1 \cos 2x + c_2 \sin 2x + \frac{1}{13}e^{3x} \quad \blacksquare \blacksquare$$

If $G(x)$ is either $C \cos kx$ or $C \sin kx$, then, because of the rules for differentiating the sine and cosine functions, we take as a trial particular solution a function of the form

$$y_p(x) = A \cos kx + B \sin kx$$

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EXAMPLE 3 Solve $y'' + y' - 2y = \sin x$.

SOLUTION We try a particular solution

$$y_p(x) = A \cos x + B \sin x$$

Then $y'_p = -A \sin x + B \cos x$ $y''_p = -A \cos x - B \sin x$

so substitution in the differential equation gives

$$(-A \cos x - B \sin x) + (-A \sin x + B \cos x) - 2(A \cos x + B \sin x) = \sin x$$

or $(-3A + B) \cos x + (-A - 3B) \sin x = \sin x$

This is true if

$$-3A + B = 0 \quad \text{and} \quad -A - 3B = 1$$

The solution of this system is

$$A = -\frac{1}{10} \quad B = -\frac{3}{10}$$

so a particular solution is

$$y_p(x) = -\frac{1}{10} \cos x - \frac{3}{10} \sin x$$

In Example 1 we determined that the solution of the complementary equation is $y_c = c_1 e^x + c_2 e^{-2x}$. Thus, the general solution of the given equation is

$$y(x) = c_1 e^x + c_2 e^{-2x} - \frac{1}{10}(\cos x + 3 \sin x) \quad \blacksquare \blacksquare$$

If $G(x)$ is a product of functions of the preceding types, then we take the trial solution to be a product of functions of the same type. For instance, in solving the differential equation

$$y'' + 2y' + 4y = x \cos 3x$$

we would try

$$y_p(x) = (Ax + B) \cos 3x + (Cx + D) \sin 3x$$

If $G(x)$ is a sum of functions of these types, we use the easily verified *principle of superposition*, which says that if y_{p_1} and y_{p_2} are solutions of

$$ay'' + by' + cy = G_1(x) \quad ay'' + by' + cy = G_2(x)$$

respectively, then $y_{p_1} + y_{p_2}$ is a solution of

$$ay'' + by' + cy = G_1(x) + G_2(x)$$

EXAMPLE 4 Solve $y'' - 4y = xe^x + \cos 2x$.

SOLUTION The auxiliary equation is $r^2 - 4 = 0$ with roots ± 2 , so the solution of the complementary equation is $y_c(x) = c_1e^{2x} + c_2e^{-2x}$. For the equation $y'' - 4y = xe^x$ we try

$$y_{p_1}(x) = (Ax + B)e^x$$

Then $y'_{p_1} = (Ax + A + B)e^x$, $y''_{p_1} = (Ax + 2A + B)e^x$, so substitution in the equation gives

$$(Ax + 2A + B)e^x - 4(Ax + B)e^x = xe^x$$

or
$$(-3Ax + 2A - 3B)e^x = xe^x$$

Thus, $-3A = 1$ and $2A - 3B = 0$, so $A = -\frac{1}{3}$, $B = -\frac{2}{9}$, and

$$y_{p_1}(x) = \left(-\frac{1}{3}x - \frac{2}{9}\right)e^x$$

For the equation $y'' - 4y = \cos 2x$, we try

$$y_{p_2}(x) = C \cos 2x + D \sin 2x$$

Substitution gives

$$-4C \cos 2x - 4D \sin 2x - 4(C \cos 2x + D \sin 2x) = \cos 2x$$

or
$$-8C \cos 2x - 8D \sin 2x = \cos 2x$$

Therefore, $-8C = 1$, $-8D = 0$, and

$$y_{p_2}(x) = -\frac{1}{8} \cos 2x$$

By the superposition principle, the general solution is

$$y = y_c + y_{p_1} + y_{p_2} = c_1e^{2x} + c_2e^{-2x} - \left(\frac{1}{3}x + \frac{2}{9}\right)e^x - \frac{1}{8} \cos 2x \quad \blacksquare \blacksquare$$

Finally we note that the recommended trial solution y_p sometimes turns out to be a solution of the complementary equation and therefore can't be a solution of the nonhomogeneous equation. In such cases we multiply the recommended trial solution by x (or by x^2 if necessary) so that no term in $y_p(x)$ is a solution of the complementary equation.

EXAMPLE 5 Solve $y'' + y = \sin x$.

SOLUTION The auxiliary equation is $r^2 + 1 = 0$ with roots $\pm i$, so the solution of the complementary equation is

$$y_c(x) = c_1 \cos x + c_2 \sin x$$

Ordinarily, we would use the trial solution

$$y_p(x) = A \cos x + B \sin x$$

but we observe that it is a solution of the complementary equation, so instead we try

$$y_p(x) = Ax \cos x + Bx \sin x$$

Then $y_p'(x) = A \cos x - Ax \sin x + B \sin x + Bx \cos x$

$$y_p''(x) = -2A \sin x - Ax \cos x + 2B \cos x - Bx \sin x$$

Substitution in the differential equation gives

$$y_p'' + y_p = -2A \sin x + 2B \cos x = \sin x$$

so $A = -\frac{1}{2}$, $B = 0$, and

$$y_p(x) = -\frac{1}{2}x \cos x$$

The general solution is

$$y(x) = c_1 \cos x + c_2 \sin x - \frac{1}{2}x \cos x$$



We summarize the method of undetermined coefficients as follows:

1. If $G(x) = e^{kx}P(x)$, where P is a polynomial of degree n , then try $y_p(x) = e^{kx}Q(x)$, where $Q(x)$ is an n th-degree polynomial (whose coefficients are determined by substituting in the differential equation.)
2. If $G(x) = e^{kx}P(x) \cos mx$ or $G(x) = e^{kx}P(x) \sin mx$, where P is an n th-degree polynomial, then try

$$y_p(x) = e^{kx}Q(x) \cos mx + e^{kx}R(x) \sin mx$$

where Q and R are n th-degree polynomials.

Modification: If any term of y_p is a solution of the complementary equation, multiply y_p by x (or by x^2 if necessary).

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EXAMPLE 6 Determine the form of the trial solution for the differential equation $y'' - 4y' + 13y = e^{2x} \cos 3x$.

SOLUTION Here $G(x)$ has the form of part 2 of the summary, where $k = 2$, $m = 3$, and $P(x) = 1$. So, at first glance, the form of the trial solution would be

$$y_p(x) = e^{2x}(A \cos 3x + B \sin 3x)$$

But the auxiliary equation is $r^2 - 4r + 13 = 0$, with roots $r = 2 \pm 3i$, so the solution of the complementary equation is

$$y_c(x) = e^{2x}(c_1 \cos 3x + c_2 \sin 3x)$$

This means that we have to multiply the suggested trial solution by x . So, instead, we use

$$y_p(x) = xe^{2x}(A \cos 3x + B \sin 3x)$$



$r(x)$	Initial guess for $y_p(x)$
k (a constant)	A (a constant)
$ax + b$	$Ax + B$ (Note: The guess must include both terms even if $b =$
$ax^2 + bx + c$	$Ax^2 + Bx + C$ (Note: The guess must include all three terms if b or c are zero.)
Higher-order polynomials	Polynomial of the same order as $r(x)$
$ae^{\lambda x}$	$Ae^{\lambda x}$
$a \cos \beta x + b \sin \beta x$	$A \cos \beta x + B \sin \beta x$ (Note: The guess must include both terms even if either $a = 0$ or $b = 0$.)
$ae^{\alpha x} \cos \beta x + be^{\alpha x} \sin \beta x$	$Ae^{\alpha x} \cos \beta x + Be^{\alpha x} \sin \beta x$
$(ax^2 + bx + c) e^{\lambda x}$	$(Ax^2 + Bx + C) e^{\lambda x}$
$(a_2x^2 + a_1x + a_0) \cos \beta x$ $+ (b_2x^2 + b_1x + b_0) \sin \beta x$	$(A_2x^2 + A_1x + A_0) \cos \beta x$ $+ (B_2x^2 + B_1x + B_0) \sin \beta x$
$(a_2x^2 + a_1x + a_0) e^{\alpha x} \cos \beta x$ $+ (b_2x^2 + b_1x + b_0) e^{\alpha x} \sin \beta x$	$(A_2x^2 + A_1x + A_0) e^{\alpha x} \cos \beta x$ $+ (B_2x^2 + B_1x + B_0) e^{\alpha x} \sin \beta x$

Variation of Parameters

Sometimes, $r(x)$ is not a combination of polynomials, exponentials, or sines and cosines. When this is the case, the method of undetermined coefficients does not work, and we have to use another approach to find a particular solution to the differential equation. We use an approach called the **method of variation of parameters**.

To simplify our calculations a little, we are going to divide the differential equation through by a , so we have a leading coefficient of 1. Then the differential equation has the form

$$y'' + py' + qy = r(x),$$

where p and q are constants.

If the general solution to the complementary equation is given by $c_1 y_1(x) + c_2 y_2(x)$, we are going to look for a particular solution of the form $y_p(x) = u(x)y_1(x) + v(x)y_2(x)$. In this case, we use the two linearly independent solutions to the complementary equation to form our particular solution. However, we are assuming that the coefficients are functions of x , rather than constants. We want to find functions $u(x)$ and $v(x)$ such that $y_p(x)$ satisfies the differential equation. We have

$$\begin{aligned} y_p &= uy_1 + vy_2 \\ y_p' &= u'y_1 + uy_1' + v'y_2 + vy_2' \\ y_p'' &= (u'y_1 + v'y_2)' + u'y_1' + uy_1'' + v'y_2' + vy_2'' \end{aligned}$$

Substituting into the differential equation, we obtain

$$\begin{aligned} y_p'' + py_p' + qy_p &= [(u'y_1 + v'y_2)' + u'y_1' + uy_1'' + v'y_2' + vy_2''] \\ &\quad + p[u'y_1 + uy_1' + v'y_2 + vy_2'] + q[uy_1 + vy_2] \\ &= u[y_1'' + py_1' + qy_1] + v[y_2'' + py_2' + qy_2] \\ &\quad + (u'y_1 + v'y_2)' + p(u'y_1 + v'y_2) + (u'y_1' + v'y_2'). \end{aligned}$$

Note that y_1 and y_2 are solutions to the complementary equation, so the first two terms are zero. Thus, we have

$$(u'y_1 + v'y_2)' + p(u'y_1 + v'y_2) + (u'y_1' + v'y_2') = r(x).$$

If we simplify this equation by imposing the additional condition $u'y_1 + v'y_2 = 0$, the first two terms are zero and this reduces to $u'y_1' + v'y_2' = r(x)$. So, with this additional condition, we have a system of two equations in two unknowns:

$$\begin{aligned} u'y_1 + v'y_2 &= 0 \\ u'y_1' + v'y_2' &= r(x). \end{aligned}$$

Solving this system gives us u' and v' , which we can integrate to find u and v .

Then, $y_p(x) = u(x)y_1(x) + v(x)y_2(x)$ is a particular solution to the differential equation. Solving this system of equations is sometimes challenging, so let's take this opportunity to review Cramer's rule, which allows us to solve the system of equations using determinants.

RULE: CRAMER'S RULE

The system of equations

$$a_1 z_1 + b_1 z_2 = r_1$$

$$a_2 z_1 + b_2 z_2 = r_2$$

has a unique solution if and only if the determinant of the coefficients is not zero. In this case, the solution is given by

$$z_1 = \frac{\begin{vmatrix} r_1 & b_1 \\ r_2 & b_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}} \quad \text{and} \quad z_2 = \frac{\begin{vmatrix} a_1 & r_1 \\ a_2 & r_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}.$$

Use Cramer's rule to solve the following system of equations.

$$x^2 z_1 + 2x z_2 = 0$$

$$z_1 - 3x^2 z_2 = 2x$$

[Show/Hide Solution]

Solution

We have

$$a_1(x) = x^2$$

$$a_2(x) = 1$$

$$b_1(x) = 2x$$

$$b_2(x) = -3x^2$$

$$r_1(x) = 0$$

$$r_2(x) = 2x.$$

Then,

$$\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} = \begin{vmatrix} x^2 & 2x \\ 1 & -3x^2 \end{vmatrix} = -3x^4 - 2x$$

$$\begin{vmatrix} r_1 & b_1 \\ r_2 & b_2 \end{vmatrix} = \begin{vmatrix} 0 & 2x \\ 2x & -3x^2 \end{vmatrix} = 0 - 4x^2 = -4x^2.$$

Thus,

$$z_1 = \frac{\begin{vmatrix} r_1 & b_1 \\ r_2 & b_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}} = \frac{-4x^2}{-3x^4 - 2x} = \frac{4x}{3x^3 + 2}.$$

In addition,

$$\begin{vmatrix} a_1 & r_1 \\ a_2 & r_2 \end{vmatrix} = \begin{vmatrix} x^2 & 0 \\ 1 & 2x \end{vmatrix} = 2x^3 - 0 = 2x^3.$$

Thus,

$$z_2 = \frac{\begin{vmatrix} a_1 & r_1 \\ a_2 & r_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}} = \frac{2x^3}{-3x^4 - 2x} = \frac{-2x^2}{3x^3 + 2}.$$

Home Work

Use Cramer's rule to solve the following system of equations.

$$\begin{aligned} 2xz_1 - 3z_2 &= 0 \\ x^2z_1 + 4xz_2 &= x + 1 \end{aligned}$$

PROBLEM-SOLVING STRATEGY

Problem-Solving Strategy: Method of Variation of Parameters

1. Solve the complementary equation and write down the general solution

$$c_1 y_1(x) + c_2 y_2(x).$$

2. Use Cramer's rule or another suitable technique to find functions $u'(x)$ and $v'(x)$ satisfying

$$\begin{aligned} u' y_1 + v' y_2 &= 0 \\ u' y_1' + v' y_2' &= r(x). \end{aligned}$$

3. Integrate u' and v' to find $u(x)$ and $v(x)$. Then, $y_p(x) = u(x)y_1(x) + v(x)y_2(x)$ is a particular solution to the equation.
4. Add the general solution to the complementary equation and the particular solution found in step 3 to obtain the general solution to the nonhomogeneous equation.

EXAMPLE 7.16**Using the Method of Variation of Parameters**

Find the general solution to the following differential equations.

a. $y'' - 2y' + y = \frac{e^t}{t^2}$

b. $y'' + y = 3\sin^2 x$

[Show/Hide Solution]**Solution**

a. The complementary equation is $y'' - 2y' + y = 0$ with associated general solution $c_1 e^t + c_2 t e^t$. Therefore, $y_1(t) = e^t$ and $y_2(t) = t e^t$. Calculating the derivatives, we get $y_1'(t) = e^t$ and $y_2'(t) = e^t + t e^t$ (step 1). Then, we want to find functions $u'(t)$ and $v'(t)$ so that

$$\begin{aligned} u' e^t + v' t e^t &= 0 \\ u' e^t + v' (e^t + t e^t) &= \frac{e^t}{t^2}. \end{aligned}$$

Applying Cramer's rule, we have

$$u' = \frac{\begin{vmatrix} 0 & t e^t \\ \frac{e^t}{t^2} & e^t + t e^t \end{vmatrix}}{\begin{vmatrix} e^t & t e^t \\ e^t & e^t + t e^t \end{vmatrix}} = \frac{0 - t e^t \left(\frac{e^t}{t^2}\right)}{e^t (e^t + t e^t) - e^t t e^t} = \frac{-\frac{e^{2t}}{t}}{e^{2t}} = -\frac{1}{t}$$

$$v' = \frac{\begin{vmatrix} e^t & 0 \\ e^t & \frac{e^t}{t^2} \end{vmatrix}}{\begin{vmatrix} e^t & t e^t \\ e^t & e^t + t e^t \end{vmatrix}} = \frac{e^t \left(\frac{e^t}{t^2}\right)}{e^{2t}} = \frac{1}{t^2} \text{ (step 2).}$$

Integrating, we get

$$\begin{aligned} u &= -\int \frac{1}{t} dt = -\ln |t| \\ v &= \int \frac{1}{t^2} dt = -\frac{1}{t} \text{ (step 3).} \end{aligned}$$

Then we have

$$\begin{aligned} y_p &= -e^t \ln |t| - \frac{1}{t} t e^t \\ &= -e^t \ln |t| - e^t \text{ (step 4).} \end{aligned}$$

The e^t term is a solution to the complementary equation, so we don't need to carry that term into our general solution explicitly. The general solution is

$$y(t) = c_1 e^t + c_2 t e^t - e^t \ln |t| \text{ (step 5).}$$

b. The complementary equation is $y'' + y = 0$ with associated general solution $c_1 \cos x + c_2 \sin x$. So, $y_1(x) = \cos x$ and $y_2(x) = \sin x$ (step 1). Then, we want to find functions $u'(x)$ and $v'(x)$ such that

$$\begin{aligned} u' \cos x + v' \sin x &= 0 \\ -u' \sin x + v' \cos x &= 3 \sin^2 x. \end{aligned}$$

Applying Cramer's rule, we have

$$u' = \frac{\begin{vmatrix} 0 & \sin x \\ 3 \sin^2 x & \cos x \end{vmatrix}}{\begin{vmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{vmatrix}} = \frac{0 - 3 \sin^3 x}{\cos^2 x + \sin^2 x} = -3 \sin^3 x$$

and

$$v' = \frac{\begin{vmatrix} \cos x & 0 \\ -\sin x & 3 \sin^2 x \end{vmatrix}}{\begin{vmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{vmatrix}} = \frac{3 \sin^2 x \cos x}{1} = 3 \sin^2 x \cos x \text{ (step 2).}$$

Integrating first to find u , we get

$$u = \int -3 \sin^3 x dx = -3 \left[-\frac{1}{3} \sin^2 x \cos x + \frac{2}{3} \int \sin x dx \right] = \sin^2 x \cos x + 2 \cos x.$$

Now, we integrate to find v . Using substitution (with $w = \sin x$), we get

$$v = \int 3 \sin^2 x \cos x dx = \int 3w^2 dw = w^3 = \sin^3 x.$$

Then,

$$\begin{aligned} y_p &= (\sin^2 x \cos x + 2 \cos x) \cos x + (\sin^3 x) \sin x \\ &= \sin^2 x \cos^2 x + 2 \cos^2 x + \sin^4 x \\ &= 2 \cos^2 x + \sin^2 x (\cos^2 x + \sin^2 x) \quad \text{(step 4).} \\ &= 2 \cos^2 x + \sin^2 x \\ &= \cos^2 x + 1 \end{aligned}$$

The general solution is

$$y(x) = c_1 \cos x + c_2 \sin x + 1 + \cos^2 x \text{ (step 5).}$$

CHECKPOINT 7.14

Find the general solution to the following differential equations.

- a. $y'' + y = \sec x$
- b. $x'' - 2x' + x = \frac{e^t}{t}$

Section 7.2 Exercises

Solve the following equations using the method of undetermined coefficients.

- 54. $2y'' - 5y' - 12y = 6$
- 55. $3y'' + y' - 4y = 8$
- 56. $y'' - 6y' + 5y = e^{-x}$
- 57. $y'' + 16y = e^{-2x}$
- 58. $y'' - 4y = x^2 + 1$
- 59. $y'' - 4y' + 4y = 8x^2 + 4x$

6.5 Cauchy–Euler Equation

Cauchy–Euler equation

One of the simplest linear variable coefficient differential equations is the homogeneous second order **Cauchy–Euler** equation, whose standard form is

$$x^2 \frac{d^2y}{dx^2} + a_1x \frac{dy}{dx} + a_2y = 0. \tag{55}$$

The solution of this homogeneous equation can be reduced to a simple algebraic problem by seeking a solution of the form

$$y(x) = Ax^m, \tag{56}$$

where A is an arbitrary constant, and the permissible values of m are to be determined.

Differentiating $y(x)$ to obtain

$$\frac{dy}{dx} = mAx^{m-1} \quad \text{and} \quad \frac{d^2y}{dx^2} = m(m-1)Ax^{m-2} \tag{57}$$

and substituting these expressions into the Cauchy–Euler equation gives the following quadratic equation for m :

$$m(m-1) + a_1m + a_2 = 0. \tag{58}$$

When this equation has two distinct real roots $m = \alpha$ and $m = \beta$, the general solution of (55) is

$$y(x) = C_1x^\alpha + C_2x^\beta, \quad (59)$$

but if the two roots are real and equal with $m = \mu$, the general solution of (55) is

$$y(x) = C_1x^\mu + C_2x^\mu \ln |x|, \quad (60)$$

where C_1 and C_2 are arbitrary real constants.

If the equation for m has the complex conjugate roots $m = \alpha \pm i\beta$, substitution confirms that the general solution of (55) is

$$y(x) = C_1x^\alpha \cos(\beta \ln |x|) + C_2x^\alpha \sin(\beta \ln |x|). \quad (61)$$

The second solution $x^\mu \ln |x|$ in (60) can be obtained from the method of Section 6.7 by using the known solution $y_1(x) = x^\mu$ to find a second linearly independent solution $y_2(x)$. The form of solution (61) follows from writing the general solution as $y(x) = A \exp(\alpha + i\beta) + B \exp(\alpha - i\beta)$, with A an arbitrary complex constant and B its complex conjugate so that $y(x)$ is real.

EXAMPLE 6.16

Find the general solution of

$$x^2 \frac{d^2y}{dx^2} + 3x \frac{dy}{dx} + 2y = 0 \quad \text{for } x \neq 0.$$

Solution The equation for m is

$$m(m - 1) + 3m + 2 = 0,$$

with the roots $m = -1 \pm i$. The general solution is thus

$$y(x) = C_1x^{-1} \cos(\ln |x|) + C_2x^{-1} \sin(\ln |x|).$$

Example

Solve differential equation $x^2y'' - 3xy' + 4y = 0$ with initial values $y(1) = 1$ and $y'(1) = 2$.

We assume that the solution is in the form $y(x) = x^m$. Then

$$\begin{aligned} y(x) &= x^m, \\ y'(x) &= mx^{m-1}, \\ y''(x) &= m(m - 1)x^{m-2}. \end{aligned}$$

Let us use the solution within given differential equation:

$$\begin{aligned} x^2 \cdot m(m-1)x^{m-2} - 3x \cdot mx^{m-1} + 4 \cdot x^m &= 0 \\ x^m((m^2 - m) - 3m + 4) &= 0 \\ x^m(m^2 - 4m + 4) &= 0 \\ m &= \{2, 2\} \end{aligned}$$

The solution of differential equation is

$$y_c(x) = c_1 x^2 + c_2 x^2 \log x.$$

In order to find values of c_1 and c_2 according to initial values, we need also y'_c :

$$\begin{aligned} y'_c(x) &= 2c_1 x + 2c_2 x \log x + c_2 x^2 \frac{1}{x} \\ &= 2c_1 x + 2c_2 x \log x + c_2 x. \end{aligned}$$

For $y(1) = 1$ and $y'(1) = 2$ we get from (1) and (2) $c_1 = 1, c_2 = 0$. The solution is then

$$\underline{\underline{y(x) = x^2.}}$$

Example

Solve differential equation $x^2 y'' - 2xy' + 2y = x^3, \quad x > 0$

Because the differential equation is in the form of Cauchy-Euler DE we assume that the solution is in the form of $y(x) = x^m$. Then

$$\begin{aligned} y(x) &= x^m, \\ y'(x) &= mx^{m-1}, \\ y''(x) &= m(m-1)x^{m-2}. \end{aligned}$$

Let us use the solution within associated homogeneous differential equation to obtain complementary function $y_c(x)$:

$$\begin{aligned} x^2 \cdot m(m-1)x^{m-2} - 2x \cdot mx^{m-1} + 2 \cdot x^m &= 0 \\ x^m(m(m-1) - 2m + 2) &= 0 \\ x^m(m^2 - 3m + 2) &= 0 \\ x^m(m-2)(m-1) &= 0 \\ m &= \{1, 2\} \end{aligned}$$

The complementary function $y_c(x)$ (i.e. the solution of associated homogeneous differential equation) is

$$\underline{\underline{y_c(x) = c_1 x + c_2 x^2.}}$$

Example

Solve differential equation $x^2y'' + 4xy' - 4y = 3$

First, let us solve associated homogeneous DE $x^2y'' + 4xy' - 4y = 0$ for y_c , then particular solution y_p .

We expect the solution in a form of $y = x^m$, then $y' = mx^{m-1}$, $y'' = m(m-1)x^{m-2}$.

$$\begin{aligned} x^2 m(m-1)x^{m-2} + 4x mx^{m-1} - 4x^m &= 0 \\ x^m [m(m-1) + 4m - 4] &= 0 \\ x^m (m^2 + 3m - 4) = 0 &\implies m = \{-4, 1\} \end{aligned}$$

The complementary function is $y_c = c_1x + c_2x^{-4}$ and particular solution $y_p = A$ has to be determined and it is pretty obvious that $A = -3/4$ (test yourself that $y_p = -3/4$ satisfies given DE).

$$y = c_1x + c_2x^{-4} - \frac{3}{4}$$

Find the general solution: $x^2y'' + 5xy' + 12y = 0$

Solution

As with the constant coefficient equations, we begin by writing down the characteristic equation. Doing a simple computation,

$$\begin{aligned} 0 &= r(r-1) + 5r + 12 \\ &= r^2 + 4r + 12 \\ &= (r+2)^2 + 8, \\ -8 &= (r+2)^2, \end{aligned}$$

one determines the roots are $r = -2 \pm 2\sqrt{2}i$. Therefore, the general solution is

$$y(x) = [c_1 \cos(2\sqrt{2} \ln |x|) + c_2 \sin(2\sqrt{2} \ln |x|)] x^{-2}$$

Find the general solution: $x^2y'' + 5xy' + 12y = 0$

Solution

As with the constant coefficient equations, we begin by writing down the characteristic equation. Doing a simple computation,

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$$y(x) = [c_1 \cos(2\sqrt{2} \ln |x|) + c_2 \sin(2\sqrt{2} \ln |x|)] x^{-2}$$

Deriving the solution for Case 2 for the Cauchy-Euler equations works in the same way as the second for constant coefficient equations, but it is a bit messier. First note that for the real root, $r = r_1$, the characteristic equation has to factor as $(r - r_1)^2 = 0$. Expanding, we have

$$r^2 - 2r_1 r + r_1^2 = 0$$

$$0 = y(1) = c_1$$

Thus, we have so far that $y(t) = c_2 \ln |t| t^{-1}$.

Now, using the second condition and

$$y'(t) = c_2(1 - \ln |t|)t^{-2}$$

we have

$$1 = y(1) = c_2$$

Therefore, the solution of the initial value problem is $y(t) = \ln |t| t^{-1}$.

We now turn to the case of complex conjugate roots, $r = \alpha \pm i\beta$. When dealing with the Cauchy-Euler equations, we have solutions of the form $y(x) = x^{\alpha+i\beta}$. The key to obtaining real solutions is to first rewrite x^y :

$$x^y = e^{\ln x^y} = e^{y \ln x}$$

Thus, a power can be written as an exponential and the solution can be written as

$$y(x) = x^{\alpha+i\beta} = x^\alpha e^{i\beta \ln x}, \quad x > 0$$

For complex conjugate roots, $r = \alpha \pm i\beta$, the general solution takes the form $y(x) = x^\alpha (c_1 \cos(\beta \ln |x|) + c_2 \sin(\beta \ln |x|))$

Recalling that

$$e^{i\beta \ln x} = \cos(\beta \ln |x|) + i \sin(\beta \ln |x|),$$

we can now find two real, linearly independent solutions, $x^\alpha \cos(\beta \ln |x|)$ and $x^\alpha \sin(\beta \ln |x|)$ following the same steps as earlier for the constant coefficient case. This gives the general solution as

$$y(x) = x^\alpha (c_1 \cos(\beta \ln |x|) + c_2 \sin(\beta \ln |x|))$$

✓ Example 2.5.3

Solve: $x^2y'' - xy' + 5y = 0$.

Solution

The characteristic equation takes the form

$$r(r - 1) - r + 5 = 0$$

or

$$r^2 - 2r + 5 = 0$$

The roots of this equation are complex, $r_{1,2} = 1 \pm 2i$. Therefore, the general solution is $y(x) = x(c_1 \cos(2 \ln |x|) + c_2 \sin(2 \ln |x|))$.

Three cases are summarized below.

♦ Classification of Roots of the Characteristic Equation for Cauchy-Euler Differential Equations

1. Real, distinct roots r_1, r_2 . In this case the solutions corresponding to each root are linearly independent. Therefore, the general solution is simply

$$y(x) = c_1 x^{r_1} + c_2 x^{r_2}.$$

2. Real, equal roots $r_1 = r_2 = r$. In this case the solutions corresponding to each root are linearly dependent. To find a second linearly independent solution, one uses the Method of Reduction of Order. This gives the second solution as $x^r \ln |x|$. Therefore, the general solution is found as

$$y(x) = (c_1 + c_2 \ln |x|) x^r.$$

3. Complex conjugate roots $r_1, r_2 = \alpha \pm i\beta$. In this case the solutions corresponding to each root are linearly independent. These complex exponentials can be rewritten in terms of trigonometric functions. Namely, one has that $x^\alpha \cos(\beta \ln |x|)$ and $x^\alpha \sin(\beta \ln |x|)$ are two linearly independent solutions. Therefore, the general solution becomes

$$y(x) = x^\alpha (c_1 \cos(\beta \ln |x|) + c_2 \sin(\beta \ln |x|)).$$

Nonhomogeneous Cauchy-Euler Equations

We can also solve some nonhomogeneous Cauchy-Euler equations using the Method of Undetermined Coefficients or the Method of Variation of Parameters. We will demonstrate this with a couple of examples.

✓ Example 2.5.4

Find the solution of $x^2y'' - xy' - 3y = 2x^2$.

Solution

First we find the solution of the homogeneous equation. The characteristic equation is $r^2 - 2r - 3 = 0$. So, the roots are $r = -1, 3$ and the solution is $y_h(x) = c_1 x^{-1} + c_2 x^3$.

We next need a particular solution. Let's guess $y_p(x) = Ax^2$. Inserting the guess into the nonhomogeneous differential equation, we have

$$\begin{aligned} 2x^2 &= x^2y'' - xy' - 3y = 2x^2 \\ &= 2Ax^2 - 2Ax^2 - 3Ax^2 \\ &= -3Ax^2 \end{aligned}$$

So, $A = -2/3$. Therefore, the general solution of the problem is

$$y(x) = c_1 x^{-1} + c_2 x^3 - \frac{2}{3} x^2$$

Find the solution of $x^2 y'' - xy' - 3y = 2x^3$.

Solution

In this case the nonhomogeneous term is a solution of the homogeneous problem, which we solved in the last example. So, we will need a modification of the method. We have a problem of the form

$$ax^2 y'' + bxy' + cy = dx^r$$

where r is a solution of $ar(r - 1) + br + c = 0$. Let's guess a solution of the form $y = Ax^r \ln x$. Then one finds that the differential equation reduces to $Ax^r(2ar - a + b) = dx^r$. [You should verify this for yourself.]

With this in mind, we can now solve the problem at hand. Let $y_p = Ax^3 \ln x$. Inserting into the equation, we obtain $4Ax^3 = 2x^3$, or $A = 1/2$. The general solution of the problem can now be written as

$$y(x) = c_1 x^{-1} + c_2 x^3 + \frac{1}{2} x^3 \ln x$$

Find the solution of $x^2 y'' - xy' - 3y = 2x^3$ using Variation of Parameters.

Solution

As noted in the previous examples, the solution of the homogeneous problem has two linearly independent solutions, $y_1(x) = x^{-1}$ and $y_2(x) = x^3$. Assuming a particular solution of the form $y_p(x) = c_1(x)y_1(x) + c_2(x)y_2(x)$, we need to

solve the system 2.4.25:

$$\begin{aligned} c_1'(x)x^{-1} + c_2'(x)x^3 &= 0 \\ -c_1'(x)x^{-2} + 3c_2'(x)x^2 &= \frac{2x^3}{x^2} = 2x. \end{aligned}$$

From the first equation of the system we have $c_1'(x) = -x^4 c_2'(x)$. Substituting this into the second equation gives $c_2'(x) = \frac{1}{2x}$. So, $c_2(x) = \frac{1}{2} \ln |x|$ and, therefore, $c_1(x) = \frac{1}{8} x^4$. The particular solution is

$$y_p(x) = c_1(x)y_1(x) + c_2(x)y_2(x) = \frac{1}{8} x^3 + \frac{1}{2} x^3 \ln |x|$$

Adding this to the homogeneous solution, we obtain the same solution as in the last example using the Method of Undetermined Coefficients. However, since $\frac{1}{8} x^3$ is a solution of the homogeneous problem, it can be absorbed into the first terms, leaving

$$y(x) = c_1 x^{-1} + c_2 x^3 + \frac{1}{2} x^3 \ln x$$